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C7.5 General Relativity I

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Wk. 2.4.6.8 Thu 16:00 - 17:30

2017/2018

Problem Set 1

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(A+)

Very well done!

① (1+)

$$X = X^{ab} = \begin{pmatrix} 2 & 0 & 1 & -1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & 2 \end{pmatrix} \quad V = V^a = (-1 \ 2 \ 0 \ -2)$$

$$\eta = \eta_{ab} = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} = \eta^{ab}$$

$$\rightarrow X^a_b = X^{ac} \eta_{cb} = \begin{pmatrix} 2 & 0 & 1 & -1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} = \cancel{X \cdot \eta}$$

$$= \begin{pmatrix} -2 & 0 & 1 & -1 \\ 1 & 0 & 3 & 2 \\ 1 & 1 & 0 & 0 \\ 2 & 1 & 1 & -2 \end{pmatrix} \quad \text{Good!}$$

$$\rightarrow X_a^b = \cancel{\eta_{ac} \eta^{bd} X^{ca}} \eta_{ac} X^{cb} = \begin{pmatrix} -2 & 0 & -1 & 1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix}$$

$$\rightarrow X^{(ab)} = \frac{1}{2} (X^{ab} + X^{ba}) = \begin{pmatrix} 2 & -\frac{1}{2} & 0 & -\frac{3}{2} \\ -\frac{1}{2} & 0 & 2 & \frac{3}{2} \\ 0 & 2 & 0 & \frac{1}{2} \\ -\frac{3}{2} & \frac{3}{2} & \frac{1}{2} & -2 \end{pmatrix} \quad \text{Fantastic!}$$

~~$$X_{ab} = g_{ac} X^c_b = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} -2 & 0 & -1 & 1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix}$$~~

~~$$X_{ab} = g_{ac} X^c_b = g_{ac} X^{cd} g_{db} =$$~~

$$X_{ab} = \eta_{ac} X^{cd} \eta_{db} = \eta X \eta = \begin{pmatrix} 2 & 0 & -1 & 1 \\ 1 & 0 & 3 & 2 \\ 1 & 1 & 0 & 0 \\ 2 & 1 & 1 & -2 \end{pmatrix}$$

Good!

$$\rightarrow X_{[ab]} = \frac{1}{2} (X_{ab} - X_{ba}) = \begin{pmatrix} 0 & -\frac{1}{2} & -1 & -\frac{1}{2} \\ \frac{1}{2} & 0 & -1 & \frac{1}{2} \\ -1 & -1 & 0 & -\frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & 0 \end{pmatrix}$$

$$\rightarrow X^\lambda{}_\lambda = \text{tr}(X^a{}_b) = -2 + 0 + 0 - 2 = \underline{\underline{-4}}$$

Check!

~~$$\rightarrow V^a V_a = V^a V_a = g_{ab} V^b =$$~~

$$V_a = \eta_{ab} V^b = V^b \eta_{ba} = (-1 \ 2 \ 0 \ -2) \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & -1 \end{pmatrix}$$

$$= (1 \ 2 \ 0 \ -2)$$

$$\therefore V^a V_a = (-1)(1) + (2)(2) + (0)(0) + (-2)(-2)$$

$$= -1 + 4 + 4 = \underline{\underline{7}} \quad \textcircled{v}$$

~~$$\rightarrow V_a X^{ab} = V \cdot X = (0, 2, 3, 4)$$~~

$$= (4, -2, 5, -1)^+$$

(2)

(1+1)

1.  $x'^a = L^{ab} x^b$  ~~one~~

one of the ~~indices~~ index b's should be lower

$\rightarrow x'^a = L^a_b x^b$  Good!

2.  $x'^a = L^b_c M^c_d x^d$

~~free~~  $\rightarrow$  free index needs to match.

~~$x'^b = L^b_c M^c_d x^d$~~

$x'^b = L^b_c M^c_d x^d$  (✓)

3.  $\delta^a_b = \delta^a_c \delta^c_d$

free indices don't match

$\delta^a_b = \delta^a_c \delta^c_b$  (✓)

4.  $x'^a = L^a_c x^c + M^c_d x^d$

free indices don't match

$x'^a = L^a_c x^c + M^a_d x^d$  Good!

5.  $x'^a = L^a_c x^c + M^a_d x^d$

one of the d's should be lower

$x'^a = L^a_c x^c + M^a_d x^d$  Great!

$$6. \phi = (X^a A_a) (Y^a B_a)$$

same dummy indices can only appear twice

$$\phi = (X^a A_a) (Y^b B_b) \quad \text{①}$$

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(x)

A (p, q) tensor looks like:

$$T \begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix}$$

under change of coordinates  $x^a \rightarrow x'^a$ ,

T transforms like

$$T \begin{matrix} a_1, a_2, \dots, a_p \\ b_1, b_2, \dots, b_q \end{matrix} = \frac{\partial x'^{a_1}}{\partial x^{\mu_1}} \frac{\partial x'^{a_2}}{\partial x^{\mu_2}} \dots \frac{\partial x'^{a_p}}{\partial x^{\mu_p}} x \begin{matrix} \mu_1, \mu_2, \dots, \mu_p \\ \nu_1, \nu_2, \dots, \nu_q \end{matrix}$$

Good!

$$\frac{\partial x'^{\mu_1}}{\partial x'^{\nu_1}} \frac{\partial x'^{\mu_2}}{\partial x'^{\nu_2}} \dots \frac{\partial x'^{\mu_p}}{\partial x'^{\nu_p}} T \begin{matrix} \mu_1, \mu_2, \dots, \mu_p \\ \nu_1, \nu_2, \dots, \nu_q \end{matrix}$$

For Lorentz transformation

$$x'^a = \frac{\partial x'^a}{\partial x^b} x^b \quad \frac{\partial x'^a}{\partial x^b} = \Lambda^a_b$$

$$\frac{\partial x'^a}{\partial x^b} = \begin{pmatrix} \gamma & -\gamma\beta & 0 & 0 \\ -\gamma\beta & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \quad \text{with } \gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\beta = \frac{v}{c}$$

for boost along x-direction.

Great!

- To show something is a tensor, it is suffice to show that it has the correct transformation property

Given  $S'^a_b = \frac{\partial x'^a}{\partial x^\mu} \frac{\partial x^\nu}{\partial x'^b} S^\mu_\nu$ ,  $T^a_b = \frac{\partial x'^a}{\partial x^\mu} \frac{\partial x^\nu}{\partial x'^b} T^\mu_\nu$

$\rightarrow S'^a_b + T'^a_b = \left( \frac{\partial x'^a}{\partial x^\mu} \frac{\partial x^\nu}{\partial x'^b} \right) (S^\mu_\nu + T^\mu_\nu)$  Good!

$\rightarrow S^a_b + T^a_b$  is a (1,1) tensor.

Given  $S'^a_b = \frac{\partial x'^a}{\partial x^\mu} \frac{\partial x^\nu}{\partial x'^b} S^\mu_\nu$ ,  $T'^c = \frac{\partial x'^c}{\partial x^p} T^p$

$S'^a_b T'^c = \frac{\partial x'^a}{\partial x^\mu} \frac{\partial x^\nu}{\partial x'^b} S^\mu_\nu \frac{\partial x'^c}{\partial x^p} T^p = \frac{\partial x'^a}{\partial x^\mu} \frac{\partial x^\nu}{\partial x'^b} \frac{\partial x'^c}{\partial x^p} S^\mu_\nu T^p$

$\rightarrow S^a_b T^c$  is a (2,1) tensor (✓)

Given  $S'^a_{bc} = \frac{\partial x'^a}{\partial x^\mu} \frac{\partial x'^c}{\partial x^\nu} \frac{\partial x^p}{\partial x'^b} \frac{\partial x^\sigma}{\partial x'^d} S^{\mu\nu}_{p\sigma}$

Contraction: change d to c

$S'^a_{bc} = \frac{\partial x'^a}{\partial x^\mu} \left( \frac{\partial x'^c}{\partial x^\nu} \frac{\partial x^\sigma}{\partial x'^c} \right) \frac{\partial x^p}{\partial x'^b} S^{\mu\nu}_{p\sigma}$

$= \frac{\partial x'^a}{\partial x^\mu} \frac{\partial x^p}{\partial x'^b} \delta^\sigma_\nu S^{\mu\nu}_{p\sigma}$

$= \frac{\partial x'^a}{\partial x^\mu} \frac{\partial x^p}{\partial x'^b} S^{\mu\sigma}_{p\sigma}$  Good!

$S'^a_{bc}$  is a (1,1) tensor

Given  $S'^b = \frac{\partial x'^b}{\partial x^\nu} S^\nu$

$$\begin{aligned} \partial'_a S'^b &= \frac{\partial}{\partial x'^a} \left( \frac{\partial x'^b}{\partial x^\nu} S^\nu \right) = \frac{\partial x'^b}{\partial x^\nu} \frac{\partial S^\nu}{\partial x'^a} + S^\nu \frac{\partial^2 x'^b}{\partial x'^a \partial x^\nu} \\ &= \frac{\partial x'^b}{\partial x^\nu} \frac{\partial x^\nu}{\partial x'^a} \frac{\partial S^\nu}{\partial x^\nu} + S^\nu \frac{\partial^2 x'^b}{\partial x'^a \partial x^\nu} \\ &= \underbrace{\frac{\partial x'^b}{\partial x^\nu} \frac{\partial x^\nu}{\partial x'^a} \partial_\nu S^\nu}_{(1)} + \underbrace{S^\nu \frac{\partial^2 x'^b}{\partial x'^a \partial x^\nu}}_{(2)} \end{aligned}$$

term ② = 0 if  $\frac{\partial x'^b}{\partial x^\nu}$  is a constant

For Lorentz ~~transformation~~ <sup>transformation</sup> this is the case

$\therefore \partial_a S^b$  is a (1,0) tensor

For general transformation ② may  $\neq 0$

$\therefore \partial_a \partial_b S^b$  is not a tensor in general

Fantastic!



$$\begin{aligned}
 & \frac{2x^2 + 3x + 2}{x^2 + 2x + 1} = \frac{2x^2 + 3x + 2}{(x+1)^2} \\
 & = \frac{2x^2 + 4x + 2 + x}{(x+1)^2} = \frac{2(x+1)^2 + x}{(x+1)^2} \\
 & = 2 + \frac{x}{(x+1)^2} \\
 & = 2 + \frac{x}{x^2 + 2x + 1}
 \end{aligned}$$

For a zero constant term  $\theta = 0$  it is a constant  
 For a zero constant term  $\theta = 0$  it is a constant  
 For a zero constant term  $\theta = 0$  it is a constant

For general transmission  $\theta$  may be  
 For general transmission  $\theta$  may be  
 For general transmission  $\theta$  may be

(4)

(14)

completely

An anti-symmetric tensor ( $(0, m)$  tensor)

$A_{a_1 \dots a_m}$  satisfies that ~~if~~ any swap of indices generates a minus sign

i.e.

$$\cancel{A_{a_1 \dots a_i a_j \dots a_m}} = - \cancel{A_{a_1 \dots a_j a_i \dots a_m}}$$

$$- A_{a_1 \dots a_i \dots a_j \dots a_m} = A_{a_1 \dots a_j \dots a_i \dots a_m}$$

~~completely~~

Tensor in dimension  $n$  means that

$$A_{a_1 \dots a_m}, \quad \forall a_i, i \in \{1, 2, \dots, m\}, a_i \in \mathbb{Z} \\ \text{and } 1 \leq a_i \leq n$$

If  ~~$m \leq n$~~   $m > n$  :

at least two of  $\{a_1, a_2, \dots, a_m\}$  must take the same value, suppose  $a_i = a_j$  for some  $i, j \in \{1, 2, \dots, m\}$

$$A_{a_1 \dots a_i \dots a_j \dots a_m} = - A_{a_1 \dots a_j \dots a_i \dots a_m} = - A_{a_1 \dots a_i \dots a_j \dots a_m}$$

complete antisymmetry       $a_i = a_j$

~~$\neq 0$~~   
0

But if  $m \leq n$ , all  $a_i$ 's can be distinct.

Hence  ~~$(0, m)$~~   $(0, m)$  completely antisymmetric tensor

$A$  vanishes unless  $m \leq n$

- Suppose  $m \leq n$ , then ~~the~~  $\{a_1, a_2, \dots, a_m\}$  is <sup>in  $\{1, 2, \dots, n\}$</sup>   
 a subset of  $\{1, 2, \dots, n\}$

If we can independently choose the value of component  $A_{a_1, \dots, a_m}$ , ~~then~~  $\{a_1, \dots, a_m\} \subseteq \{1, 2, \dots, n\}$ , then the values of  $A_{\sigma(a_1), \sigma(a_2), \dots, \sigma(a_m)}$  are ~~determined~~ fixed for all permutations  $\sigma$  of set  $\{a_1, \dots, a_m\}$  because any swap of indices simply generates a minus sign.

- All components with at least 2 equal indices are 0 as proven before

$\therefore$  the problem reduces to how many subsets of  $m$  ~~the~~ distinct elements  $\{a_1, \dots, a_m\}$  are there in  $\{1, \dots, n\}$

The answer is  $\binom{n}{m} = \frac{n!}{m!(n-m)!}$   
*Great work!*

In an inertial frame the metric  $g^{\mu\nu} = \eta^{\mu\nu} = \text{diag}(-1, 1, 1, 1)$   $\therefore \det(g) = g = -1$

$\therefore \epsilon_{0123} = \sqrt{-(-1)} = 1$   
1 *Fantastic!*

In 4D  $\epsilon_{abcd}$  has  $\binom{4}{4} = 1$  independent coordinate, and is set to  $\sqrt{-g}$

$\therefore$  the tensor is completely determined.

In general coordinate transformations

$$x \rightarrow x'(x)$$

we look at the form of

$$\epsilon_{abcd} = \frac{\partial x^\mu}{\partial x'^a} \frac{\partial x^\nu}{\partial x'^b} \frac{\partial x^\rho}{\partial x'^c} \frac{\partial x^\sigma}{\partial x'^d} \epsilon_{\mu\nu\rho\sigma} = \epsilon_{abcd}$$

consider swapping only a, b

$$\begin{aligned} \epsilon_{bacd} &= \frac{\partial x^\mu}{\partial x'^b} \frac{\partial x^\nu}{\partial x'^a} \epsilon_{\mu\nu\rho\sigma} \frac{\partial x^\rho}{\partial x'^c} \frac{\partial x^\sigma}{\partial x'^d} \\ &= \frac{\partial x^\nu}{\partial x'^b} \frac{\partial x^\mu}{\partial x'^a} \epsilon_{\nu\mu\rho\sigma} \frac{\partial x^\rho}{\partial x'^c} \frac{\partial x^\sigma}{\partial x'^d} \\ &= \frac{\partial x^\mu}{\partial x'^a} \frac{\partial x^\nu}{\partial x'^b} \underbrace{\epsilon_{\nu\mu\rho\sigma}}_{=-\epsilon_{\mu\nu\rho\sigma}} \frac{\partial x^\rho}{\partial x'^c} \frac{\partial x^\sigma}{\partial x'^d} \\ &= -\epsilon_{adcb} \end{aligned}$$

exchange  
dummy's  $\mu, \nu$

Fantastic!

$\rightarrow$  complete anti-symmetry is preserved. ①

Now consider

$$\epsilon_{0123} = \frac{\partial x^\mu}{\partial x'^0} \frac{\partial x^\nu}{\partial x'^1} \frac{\partial x^\rho}{\partial x'^2} \frac{\partial x^\sigma}{\partial x'^3} \epsilon_{\mu\nu\rho\sigma}$$

~~this is precisely the definition of~~

we normalise  $\epsilon$  to get  $\tilde{\epsilon}_{\mu\nu\rho\sigma} = \frac{\epsilon_{\mu\nu\rho\sigma}}{\sqrt{-g}} = \begin{cases} 1 & 0123 \\ -1 & 1023 \\ 0 & 0023 \\ \dots & \dots \end{cases}$

tense

$$\therefore \frac{E_{0123}}{\sqrt{-g}} = \cancel{\epsilon_{0123}} \tilde{\epsilon}_{\mu\nu\rho\sigma} \frac{\partial x^\mu}{\partial x'^0} \frac{\partial x^\nu}{\partial x'^1} \frac{\partial x^\rho}{\partial x'^2} \frac{\partial x^\sigma}{\partial x'^3}$$

this is precisely the definition of the determinant of the 4x4 matrix  $\frac{\partial x^\alpha}{\partial x'^\beta} = \left( \frac{\partial x}{\partial x'} \right)^\alpha_\beta = \frac{\partial x^\alpha}{\partial x'^\beta}$

consider the transformation:

$$\cancel{g'_{ab}} g'_{ab} = \frac{\partial x^\mu}{\partial x'^a} \frac{\partial x^\nu}{\partial x'^b} g_{\mu\nu} \quad \text{Good!}$$

$$= \frac{\partial x^\mu}{\partial x'^a} g_{\mu\nu} \frac{\partial x^\nu}{\partial x'^b} = \left( \frac{\partial x}{\partial x'} \right)^T g \frac{\partial x}{\partial x'}$$

$$\begin{aligned} g' &= \det(g'_{ab}) = \det \left( \left( \frac{\partial x}{\partial x'} \right)^T \right) \det(g) \det \left( \frac{\partial x}{\partial x'} \right) \\ &= \det^2 \left( \frac{\partial x}{\partial x'} \right) \det(g) \\ &= g \end{aligned}$$

$$\therefore \det^2 \left( \frac{\partial x}{\partial x'} \right) = \frac{g'}{g} \Rightarrow \det \left( \frac{\partial x}{\partial x'} \right) = \sqrt{\frac{g'}{g}}$$

$$\therefore \frac{E_{0123}}{\sqrt{-g}} = \det \left( \frac{\partial x}{\partial x'} \right) = \sqrt{\frac{g'}{-g}}$$

$$\Rightarrow \underline{\underline{E_{0123} = \sqrt{-g'}}} \quad \textcircled{2}$$

$\therefore \textcircled{1}, \textcircled{2} \quad \therefore E_{0123} = \epsilon'_{0123}, \quad \cancel{\epsilon_{abcd}} E_{abcd} = \epsilon'_{abcd}$

$\therefore \epsilon'_{abcd}$  and  $\epsilon_{abcd}$  are related by

tensor transformation

$$\epsilon'_{abcd} = \frac{\partial x^\mu}{\partial x'^a} \frac{\partial x^\nu}{\partial x'^b} \frac{\partial x^\rho}{\partial x'^c} \frac{\partial x^\sigma}{\partial x'^d} \epsilon_{\mu\nu\rho\sigma}$$

$\therefore \epsilon_{abcd}$  is a general ~~tensor~~ (0,4)  
tensor.

Fantastic work!

(41)  
(5)

transformation

$$x^2 + 3x + 2 = (x+1)(x+2)$$

is a general (6.4)

transformation

5

(14)

$$\partial_a [a F_{bc}] \equiv \frac{1}{3!} (\partial_a F_{bc} - \partial_a F_{cb} + \partial_b F_{ac} - \partial_b F_{ca} + \partial_c F_{ab} - \partial_c F_{ba}) = 0$$

$$\Leftrightarrow \partial_a F_{bc} - \partial_a F_{cb} + \partial_b F_{ac} - \partial_b F_{ca} + \partial_c F_{ab} - \partial_c F_{ba} = 0$$

$$\therefore F_{ab} = -F_{ba}$$

$$\Leftrightarrow \cancel{2\partial_a F_{bc}} + 2\partial_b F_{ca} + 2\partial_c F_{ab} = 0$$

$$\Leftrightarrow \partial_a F_{bc} + \partial_b F_{ca} + \partial_c F_{ab} = 0 \quad \square$$

Great! ~~scribble~~

$$\begin{aligned} \rightarrow E_a = F_{ab} V^b & \quad \therefore E_a V^a = F_{ab} V^b V^a \\ & = F_{ba} V^a V^b \\ & \xrightarrow{\text{swap } a, b} = \cancel{F_{ba}} F_{ba} V^b V^a \\ & = -F_{ab} V^b V^a = -E_a V^a = 0 \\ \therefore E_a V^a = 0 & \quad \textcircled{1} \text{ Good!} \end{aligned}$$

$E_a$  has 4 components but 1 constraint  $\textcircled{1}$ , so it has 3 independent components  $\square$

$$\rightarrow \text{Similarly } B_a = -\frac{1}{2} \epsilon_{abcd} F^{bc} V^d$$

$$\begin{aligned} B_a V^a &= -\frac{1}{2} \epsilon_{abcd} F^{bc} V^d V^a \\ &= -\frac{1}{2} \epsilon_{dbca} F^{bc} V^a V^d = -\frac{1}{2} \underbrace{\epsilon_{dbca}}_{-f_{abcd}} F^{bc} V^d V^a \\ &= -\left[ -\frac{1}{2} \epsilon_{abcd} F^{bc} V^d V^a \right] = -B_a V^a = 0 \end{aligned}$$

Fantastic!



$\therefore B_a V^a = 0$   $\therefore$  similarly  $B_a$  has only 3 independent components  $\underline{\underline{0}}$

$\rightarrow$  ~~in~~ rest observer in inertial frame  $\circ$

$$V^a = (1, 0, 0, 0)$$

$$\therefore \bar{E}_a = F_{ab} V^b \quad \therefore \bar{E}_0 = F_{00} V^0 + F_{01} V^1 + F_{02} V^2 + F_{03} V^3$$

$$\therefore E_a = F_{a0} V^0 + F_{a1} V^1 + F_{a2} V^2 + F_{a3} V^3$$

$$\therefore V^1 = V^2 = V^3 = 0 \quad \therefore E_a = F_{a0} V^0$$

$$\therefore \bar{E}_0 = F_{00} V^0 \quad \therefore F_{ab} = -F_{ba} \quad \therefore \text{when } a=b$$

$$, F_{aa} \text{ (No sum)} = 0 \rightarrow F_{00} = 0$$

$$\therefore \underline{\underline{\bar{E}_0 = 0}} \Rightarrow \underline{\underline{E_a = (0, \vec{E})}} \quad \circ \text{ Great!}$$

$$B_a = -\frac{1}{2} \epsilon_{abcd} F^{bc} V^d \quad \text{similarly } \therefore V^1 = V^2 = V^3 = 0$$

$$\therefore \underline{\underline{B_a = -\frac{1}{2} \epsilon_{abco} F^{bc} V^o}} \quad B_a = -\frac{1}{2} \epsilon_{abco} F^{bc} V^o$$

$\therefore \epsilon_{abcd}$  is completely anti-symmetric

$$\therefore \epsilon_{obcd} = 0$$

$$\therefore B_0 = -\frac{1}{2} \epsilon_{obco} F^{bc} V^o = 0$$

$$\therefore \underline{\underline{B_a = (0, \vec{B})}} \quad \circ \text{ Good!}$$

For ~~E<sub>i</sub>~~  $E_i$  ( $i = 1, 2, 3$ ) :

$$E_i = F_{i0} \underbrace{V^0}_{=1} = \underline{\underline{F_{i0}}}$$

For  $B_i$  ( $i = 1, 2, 3$ ) :

$$B_i = \cancel{\epsilon_{i0bc}} - \frac{1}{2} \epsilon_{i0bc} F^{bc} V^0 = \underline{\underline{-\frac{1}{2} \epsilon_{ai}}} = -\frac{1}{2} \epsilon_{ijk0} \underbrace{F^{jk} V^0}_{=1}$$

the sign of Levi-Civita tensor depends on the number of swaps from ~~0123~~ the increasing order.  
Good!

$$\epsilon_{0123} = \epsilon_{123} = 1 \quad \text{for } g_{ab} = (-1, 1, 1, 1)$$

$\therefore \epsilon_{0ijk} = \epsilon_{ijk}$  for they have gone through same number of swaps from 0123 and 123 respectively.

$$\cancel{\epsilon_{ijk}} \therefore \epsilon_{ijk} = \epsilon_{0ijk} = -\epsilon_{iojk} = \epsilon_{ijok} = -\epsilon_{ijko}$$

$$\therefore B_i = -\frac{1}{2} \epsilon_{ijko} F^{jk}$$

$$= \underline{\underline{\frac{1}{2} \epsilon_{ijk} F^{jk}}}$$

$$\rightarrow \cancel{\partial_a F^{ab} = 4\pi J^b}$$

$$b=0 : \cancel{\partial_0 F^{00} + \partial_1 F^{10} + \partial_2 F^{20} + \partial_3 F^{30} =}$$

$$\downarrow \quad \downarrow \quad \downarrow$$

$$=0 \quad \frac{\partial}{\partial x}$$

~~Consider F~~

$$\begin{aligned}\partial_a F^{ab} &= g_{ac} \partial^c F^{ab} = \cancel{g_{ac} g^{\mu\nu} \partial^c F_a^b} \\ &= g_{ac} \underbrace{g^{\mu\nu}}_{\delta_c^\mu} \partial^c F_\nu^b = \delta_c^\mu \partial^c F_\nu^b = \partial^\mu F_\nu^b \\ &= \partial^a F_a^b\end{aligned}$$

$$\therefore \partial^a F_a^b = -4\pi J^b \quad \text{lower } b \text{ on both sides.}$$

$$g_{bc} \partial^a F_a^c = g_{bc} (-4\pi J^b) \Rightarrow \partial^a F_{ab} = -4\pi J_b$$

$$J_b = g_{bc} J^c = \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} \rho \\ \vec{j} \end{pmatrix} = (\rho, \vec{j}) \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

$$\partial^a = g^{ab} \partial_b = (-\rho, \vec{j})$$

$$= \left( +\frac{1}{c} \frac{\partial}{\partial t}, \vec{\nabla} \right) \begin{pmatrix} -1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix}$$

$$= \left( -\frac{1}{c} \frac{\partial}{\partial t}, \vec{\nabla} \right)$$

$$\therefore \partial^a F_{ab} = -4\pi J_b \quad \therefore$$

If  $b=0$

$$\partial^0 F_{00} + \partial^1 F_{10} + \partial^2 F_{20} + \partial^3 F_{30} = -4\pi J_0$$

$$\rightarrow 0 + \frac{\partial E_x}{\partial x} + \frac{\partial E_y}{\partial y} + \frac{\partial E_z}{\partial z} = -4\pi (-\rho)$$

$$\rightarrow \underline{\nabla \cdot \vec{E} = 4\pi \rho} \quad (M1)$$

Correct!

$$\text{If } b=i \quad (i=1,2,3)$$

$$\partial^\alpha F_{\alpha i} = -4\pi J_i$$

$$\partial^0 F_{0i} + \partial^1 F_{1i} + \partial^2 F_{2i} + \partial^3 F_{3i} = -4\pi J_i$$

$$\begin{aligned} \partial^0 F_{0i} &= -\frac{1}{c} \frac{\partial}{\partial t} F_{0i} = \frac{1}{c} \frac{\partial E_i}{\partial t} \\ &\downarrow \\ &= -F_{i0} = -E_i \end{aligned}$$

~~$$B_k = \frac{1}{2} \epsilon_{kji} F^{ji}$$~~

~~$$\begin{aligned} \text{For } k=1 \quad B_1 &= \frac{1}{2} (\epsilon_{123} F^{23} + \epsilon_{132} F^{32}) \\ &= \frac{1}{2} (F^{23} - F^{32}) \end{aligned}$$~~

$$B_i = \frac{1}{2} \epsilon_{ijk} F^{jk} \quad \therefore B^i = \frac{1}{2} \epsilon^{ijk} F_{jk}$$

( $\because$  in 3D subspace metric is  $(1,1,1)$ ,  
up/down doesn't matter)

Good! Keep it up.

consider:

$$\epsilon_{lmi} B^i = \frac{1}{2} \epsilon_{lmi} \epsilon^{ijk} F_{jk}$$

( $\epsilon, \delta$  identity)  $\rightarrow = \frac{1}{2} (\delta_l^i \delta_m^k - \delta_l^k \delta_m^i) F_{jk} = \frac{1}{2} (F_{lm} - F_{ml})$

F anti-symmetric  $\rightarrow = -F_{ml}$   
symmetric

$$\Rightarrow (F_{ij} = -\epsilon_{jik} B^k = \epsilon_{ijk} B^k)$$

$$\therefore \epsilon_{lmi} \partial^m B^i = -\partial^m F_{ml} \quad (m, l = 1, 2, 3)$$

$$\rightarrow -\epsilon_{ijk} \partial^j B^k = +\partial^j F_{ji} = \partial^1 F_{1i} + \partial^2 F_{2i} + \partial^3 F_{3i}$$

$$= -(\vec{\nabla} \times \vec{B})_i \quad (\checkmark)$$

∴ We have

$$\frac{1}{c} \frac{\partial E_i}{\partial t} - (\vec{\nabla} \times \vec{B})_i = -4\pi J_i$$

$$\therefore \vec{\nabla} \times \vec{B} = 4\pi \vec{J} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t} \quad (M4)$$

Fantastic.

$$\rightarrow \partial [aF_{bc}] = 0 \quad (\Leftrightarrow) \quad \partial_a F_{bc} + \partial_b F_{ca} + \partial_c F_{ab} = 0$$

From previous page we know that

~~$$\partial_a F_{bc} = \partial_a F_{bc}$$~~

$$\partial_i F_{jk} = \partial_i [ + \epsilon_{jkl} B^l ]$$

$$= + \epsilon_{jkl} \partial_i B^l$$

For  $a, b, c = i, j, k = \{1, 2, 3\}$  :

$$\partial_i F_{jk} + \partial_j F_{ki} + \partial_k F_{ij} = 0$$

$$\therefore + \epsilon_{jke} \partial_i B^e + \epsilon_{kim} \partial_j B^m + \epsilon_{ijn} \partial_k B^n = 0$$

\* contract with  $\epsilon^{ijk}$

$$\therefore \epsilon^{ijk} \epsilon_{jke} \partial_i B^e + \epsilon^{ijk} \epsilon_{kim} \partial_j B^m + \epsilon^{ijk} \epsilon_{ijn} \partial_k B^n = 0$$

$$\begin{aligned} \epsilon^{ijk} \epsilon_{ijm} &= 2\delta^{km} \\ \epsilon^{ijk} \epsilon_{ijm} &= 2\delta^k_m \end{aligned}$$

$$2\delta^{ii} \partial_i B^i + 2\delta^{jj} \partial_j B^j + 2\delta^{kk} \partial_k B^k = 0$$

$$\therefore \partial_i B^i + \partial_m B^m + \partial_n B^n = 0$$

$$\rightarrow 3\partial_i B^i = 0 \rightarrow \partial_i B^i = 0 \rightarrow \vec{\nabla} \cdot \vec{B} = 0$$

$$\Rightarrow \vec{\nabla} \cdot \vec{B} = 0 \quad (M2)$$

For  $a, b, c = 0, i, j$  ( $i, j = \{1, 2, 3\}$ )

if  $a=0, b, c = i, j$

$$\partial_0 F_{ij} + \partial_i F_{j0} + \partial_j F_{0i} = 0$$

$$F_{ij} = \epsilon_{ijk} B^k \quad \therefore \partial_0 F_{ij} = \epsilon_{ijk} \partial_0 B^k = \epsilon_{ijk} \left( \frac{1}{c} \frac{\partial B^k}{\partial t} \right)$$

$$\partial_i F_{j0} + \partial_j F_{0i} = \partial_i E_j - \partial_j E_i = \epsilon_{ijk} (\nabla \times \underline{E})^k$$

$$E_j = -F_{j0} = -E_j$$

$$\therefore \epsilon_{ijk} \left[ \nabla \times \underline{E} + \frac{\partial \underline{B}}{\partial t} \right]^k = 0 \quad \text{Good!}$$

$$\epsilon^{ijl} \epsilon_{ijk} \left[ \nabla \times \underline{E} + \frac{\partial \underline{B}}{\partial t} \right]^k = 0$$

$2 \delta_{lk}$

$$\therefore \left( \nabla \times \underline{E} + \frac{\partial \underline{B}}{\partial t} \right)^l = 0 \quad (l = 1, 2, 3)$$

$$\therefore \nabla \times \underline{E} + \frac{\partial \underline{B}}{\partial t} = 0 \rightarrow \nabla \times \underline{E} = - \frac{\partial \underline{B}}{\partial t} \quad (M3)$$

$$\partial_a F^{ab} = -4\pi J^b \quad \therefore \partial_b F^{ba} = -4\pi J^a$$

$$\therefore \partial_a \partial_b F^{ba} = -4\pi \partial_a J^a$$

$$\partial_a \partial_b F^{ba} = \partial_b \partial_a F^{ab} = \partial_a \partial_b F^{ab} = - \partial_a \partial_b F^{ba}$$

swap a, b      partial derivatives commute       $F_{ab} = -F_{ba}$

$$\Rightarrow \partial_a J^a = 0 \quad \text{Good!}$$

$$\partial_a \partial_a T^a = 0 \rightarrow \frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{j} = 0$$

The continuity equation, represents charge conservation

①

Energy - momentum tensor

$$T^{ab} = \frac{1}{4\pi} [F^{ac} F^b{}_c - \frac{1}{4} (F^{cd} F_{cd}) \eta^{ab}]$$

$$\partial_a T^{ab} = \frac{1}{4\pi} [ \partial_a (F^{ac} F^b{}_c) - \frac{1}{4} \eta^{ab} \partial_a (F^{cd} F_{cd}) ]$$

$$= \frac{1}{4\pi} [ \cancel{\eta} \cancel{\partial_a F^{ac}} \cancel{F^b{}_c} ]$$

$$= \frac{1}{4\pi} [ (\partial_a F^{ac}) F^b{}_c + F^{ac} \partial_a F^b{}_c - \frac{1}{4} \eta^{ab} ( (\partial_a F^{cd}) F_{cd} + F^{cd} (\partial_a F_{cd}) ) ]$$

$$\therefore \partial_a F^{ac} = -4\pi J^c \quad \text{they are equal} = 2 F^{cd} \partial_a F_{cd}$$

$$\therefore \frac{1}{4\pi} (\partial_a F^{ac}) F^b{}_c = -J^c F^b{}_c = -F^b{}_c J^c$$

consider the rest of the terms:  $\frac{1}{4\pi} M^b$

$$M^b = F^{ac} \partial_a F^b{}_c - \frac{1}{2} \eta^{ab} F^{cd} \partial_a F_{cd}$$

$$= F^{ac} \eta^{b\beta} (\partial_a F_{\beta c}) - \frac{1}{2} \eta^{ab} F^{\beta c} (\partial_a F_{\beta c})$$

(by simple index relabelling)

$$\therefore M^b = -F^{ac} \eta^{b\beta} (\partial_a F_{c\beta}) + \frac{1}{2} \eta^{ab} F^{\beta c} (\partial_\beta F_{ca} + \partial_c F_{a\beta})$$

$$F_{\beta c} = -F_{c\beta}$$

$$\partial_a F_{\beta c} + \partial_\beta F_{ca} + \partial_c F_{a\beta} = 0$$

$$= \frac{1}{2} ( - F^{ac} \eta^{b\beta} \partial_a F_{c\beta} + \eta^{ab} F^{\beta c} \partial_\beta F_{ca} )$$

②

$$+ \frac{1}{2} ( - F^{ac} \eta^{b\beta} \partial_a F_{c\beta} + \eta^{ab} F^{\beta c} \partial_c F_{a\beta} )$$

②

$$\therefore \eta^{ab} F^{\beta c} \partial_\beta F_{ca} = F^{ac} \eta^{b\beta} \partial_a F_{c\beta} \quad \therefore \Rightarrow \quad \textcircled{1} = 0$$

swap  $a, \beta$   
 $\eta^{ab} = \eta^{ba}$

$$\eta^{ab} F^{\beta c} \partial_c F_{a\beta} = F^{\beta c} \partial_c F^b_\beta = F^{ca} \partial_a F^b_c$$

$\beta \rightarrow c$   
 $c \rightarrow a$   
Good!

~~$$F^{ac} \eta^{b\beta} \partial_a F_{c\beta} = F^{ac} \partial_a F^b_c = F^{ac} \partial_a F^b_c$$~~

$$F^{ac} \eta^{b\beta} \partial_a F_{c\beta} = F^{ac} \partial_a F^b_c = (-F^{ca}) \partial_a (-F^b_c)$$

$$= F^{ca} \partial_a F^b_c$$

$$\therefore \Rightarrow \quad \textcircled{2} = 0$$

$$\therefore \quad \textcircled{1} = \textcircled{2} = 0$$

$$\therefore M^b = 0$$

Great!



(6)

$$\therefore \underline{\underline{\partial_a T^{ab} = -F^b_c J^c}}$$

- If  ~~$J^a$~~   $J^c = 0$ , then  $\partial_a T^{ab} = 0$  conserved

If  $J^c \neq 0$ , the energy and momentum are not conserved because the presence of charge and current densities.

~~may~~ electromagnetic fields do work and provides impulse on charged particles and ~~lose~~ lose energy and ~~energy~~ momentum (strictly speaking only  $\vec{E}$  field does work)

Good!

Although, the energy and momentum are conserved when we consider

$$L = L_{EM} + L_{MATTER} + L_{coupling}$$

i.e., the energy/momentum lost by the EM field is transferred to the matter system.

(6) (1+) For  $x^a(s)$  to be time-like,

$$g_{ab} \dot{x}^a \dot{x}^b < 0 \quad \forall s \in S_1 \leq s \leq S_2$$

where  $\dot{x}^a = \frac{dx^a}{ds}$

$$g_{ab} = \eta_{ab} = \text{diag}(-1, 1, 1, 1)$$

proper time

good!

in Minkowski spacetime.

$$\Delta\tau = \int_{S_1}^{S_2} (-\eta_{ab} \dot{x}^a \dot{x}^b)^{\frac{1}{2}} ds$$

variational approach:

$$\Delta\tau + \delta(\Delta\tau) = \int_{S_1}^{S_2} (-\eta_{ab} (\dot{x}^a + \delta\dot{x}^a) (\dot{x}^b + \delta\dot{x}^b))^{\frac{1}{2}} ds$$

$$= \int_{S_1}^{S_2} (-\eta_{ab} \dot{x}^a \dot{x}^b - \eta_{ab} \dot{x}^a \delta\dot{x}^b - \eta_{ab} \delta\dot{x}^a \dot{x}^b - \eta_{ab} \delta\dot{x}^a \delta\dot{x}^b)^{\frac{1}{2}} ds$$

$\eta_{ab} \dot{x}^a \delta\dot{x}^b = \eta_{ba} \dot{x}^b \delta\dot{x}^a = \eta_{ab} \delta\dot{x}^a \dot{x}^b$   
 swap a,b       $\eta_{ab} = \eta_{ba}$       correct!  
 2nd order too small

$$= \int_{S_1}^{S_2} (-\eta_{ab} \dot{x}^a \dot{x}^b - 2\eta_{ab} \dot{x}^a \delta\dot{x}^b)^{\frac{1}{2}} ds$$

$$= \int_{S_1}^{S_2} ds (-\eta_{ab} \dot{x}^a \dot{x}^b)^{\frac{1}{2}} \left( 1 - \frac{2\eta_{ab} \dot{x}^a \delta\dot{x}^b}{(-\eta_{ab} \dot{x}^a \dot{x}^b)} \right)^{\frac{1}{2}}$$

$$= \int_{S_1}^{S_2} ds \underbrace{(-\eta_{ab} \dot{x}^a \dot{x}^b)^{\frac{1}{2}}}_{\Delta\tau} \left[ 1 - \frac{\eta_{ab} \dot{x}^a \delta\dot{x}^b}{(\sqrt{-\eta_{ab} \dot{x}^a \dot{x}^b})^2} \right]$$

$$\Rightarrow \delta(\mathcal{L}) = - \int_{s_1}^{s_2} ds \frac{\eta_{ab} \dot{x}^a \delta x^b}{\sqrt{-\eta_{ab} \dot{x}^a \dot{x}^b}} = - \int_{s_1}^{s_2} ds \frac{\eta_{ab} \dot{x}^a \frac{d}{ds} \delta x^b}{\sqrt{-\eta_{ab} \dot{x}^a \dot{x}^b}}$$

$$= \underbrace{- \left[ \frac{\eta_{ab} \dot{x}^a \delta x^b}{\sqrt{-\eta_{ab} \dot{x}^a \dot{x}^b}} \right]_{\delta x^b(s_1)}^{\delta x^b(s_2)}}_{=0} + \int_{s_1}^{s_2} ds \frac{d}{ds} \left( \frac{\eta_{ab} \dot{x}^a}{\sqrt{-\eta_{ab} \dot{x}^a \dot{x}^b}} \right) \delta x^b$$

= 0 (good!)  
 $\therefore$  end points fixed

for any  $\delta x^b(s)$ , extremal proper time occurs at

$$\delta(\mathcal{L}) = 0 \quad \therefore \frac{d}{ds} \left( \frac{\eta_{ab} \dot{x}^a}{\sqrt{-\eta_{ab} \dot{x}^a \dot{x}^b}} \right) = 0$$

$$\therefore \frac{\eta_{ab} \dot{x}^a}{\sqrt{-\eta_{ab} \dot{x}^a \dot{x}^b}} = c^a \quad \checkmark \quad \text{constant vector}$$

such that  $\eta_{ab} c^a c^b = -1$

the tangent of the curve  $\dot{x}^a(s)$  is always pointing to the direction of constant vector  $c^a$

$\rightarrow$  the path is a straight line. (good!)

By reverse triangle inequality (good!) in Minkowski spacetime, straight line has the longest "distance" between two events. in  $M_4$ .

$\rightarrow$  this is ~~a~~ maximum. (good!)

we may reparametrize the curve using  $s'$

$$\dot{x}^a(s') = \frac{dx^a(s')}{ds'} = \frac{\partial s}{\partial s'} \frac{dx^a(s)}{ds}$$

$$\parallel \quad \parallel$$

$$\dot{x}^a(s') \quad \dot{x}^a(s)$$

$$\text{So } \sqrt{-\eta_{ab} \dot{x}^a(s') \dot{x}^b(s')} = \sqrt{-\eta_{ab} \frac{\partial s}{\partial s'} \dot{x}^a(s) \frac{\partial s}{\partial s'} \dot{x}^b(s)}$$

$$= \frac{\partial s}{\partial s'} \sqrt{-\eta_{ab} \dot{x}^a(s) \dot{x}^b(s)}$$

We can freely choose the function  $S(s)$  so that we can freely choose  $\frac{\partial s}{\partial s'}$  to make  $\sqrt{-\eta_{ab} \dot{x}^a(s') \dot{x}^b(s')}$  constant.  $s'$  is affine parameter.

Consider the function  $S = -\frac{1}{2} \int_{s_1}^{s_2} ds \eta_{ab} \dot{x}^a \dot{x}^b$

for an affine parameter  $s$ ,

Good!

Variational principle

$$S + \delta S = -\frac{1}{2} \int_{s_1}^{s_2} ds \eta_{ab} (\dot{x}^a + \delta \dot{x}^a) (\dot{x}^b + \delta \dot{x}^b)$$

$$= -\frac{1}{2} \int_{s_1}^{s_2} ds \eta_{ab} \dot{x}^a \dot{x}^b - \int_{s_1}^{s_2} ds \eta_{ab} \dot{x}^a \delta \dot{x}^b$$

$$+ O(\delta \dot{x}^2) \Rightarrow \cancel{S} - \delta S$$

$$= S - \int_{s_1}^{s_2} ds \eta_{ab} \dot{x}^a \delta \dot{x}^b = S + \delta S ..$$

$$\rightarrow 0 = \delta S = - \int_{s_1}^{s_2} ds \eta_{ab} \dot{x}^a \delta \dot{x}^b$$

$$= - \underbrace{\left[ \eta_{ab} \dot{x}^a \delta x^b \right]_{\delta x^b(s_1)}^{\delta x^b(s_2)}}_{=0} + \int_{s_1}^{s_2} ds \frac{d}{ds} (\eta_{ab} \dot{x}^a) \delta x^b$$

For arbitrary  $\delta x^b$ , this is 0 Fantastic!

$$\therefore \frac{d}{ds} (\eta_{ab} \dot{x}^a) = 0 \quad \therefore \eta_{ab} \dot{x}^a = c^a = \text{const.}$$

$$\therefore \sqrt{-\eta_{ab} \dot{x}^a \dot{x}^b} = \text{const} \quad \text{for affine parameter } s$$

$$\therefore \frac{\eta_{ab} \dot{x}^a}{\sqrt{-\eta_{ab} \dot{x}^a \dot{x}^b}} = c^a = \text{const.}$$

$\Rightarrow$  equivalent to extremising proper time.

If  $s, s'$  are both affine parameters, then they are restricted by

$$\underline{s' = as + b}$$

so that  $\frac{\partial s}{\partial s'} = \text{constant} = a.$

$$S = - \int_{s_1}^{s_2} ds \left[ \frac{m}{2} \eta_{ab} \dot{x}^a \dot{x}^b - q A_a \dot{x}^a \right]$$

= -L where L is the Lagrangian

general variational approach :

Euler-Lagrange equation :  $\frac{d}{ds} \left( \frac{\partial L}{\partial \dot{x}^\mu} \right) = \frac{\partial L}{\partial x^\mu}$

$$\therefore \frac{d}{ds} \left( \frac{1}{2} m \left( \eta_{ab} \frac{\partial \dot{x}^a}{\partial \dot{x}^\mu} \dot{x}^b + \eta_{ab} \dot{x}^a \frac{\partial \dot{x}^b}{\partial \dot{x}^\mu} \right) - q \frac{\partial}{\partial \dot{x}^\mu} (A_a \dot{x}^a) \right) = \frac{\partial L}{\partial x^\mu}$$

$$\therefore \frac{d}{ds} \left( \frac{1}{2} m \eta_{ab} (\delta^a_\mu \dot{x}^b + \delta^b_\mu \dot{x}^a) - q A_a \delta^a_\mu \right) = q \dot{x}^a \frac{\partial A_a}{\partial x^\mu}$$

$$\therefore m \ddot{x}^\mu - q \frac{dA_\mu}{ds} = q \dot{x}^a \partial_\mu A_a$$

$$\frac{dA_\mu}{ds} = \frac{\partial A_\mu}{\partial x^\lambda} \frac{dx^\lambda}{ds} = \dot{x}^\lambda \partial_\lambda A_\mu = \dot{x}^a \partial_a A_\mu$$

$$\therefore m \ddot{x}_\mu - q \dot{x}^a \partial_a A_\mu = q \dot{x}^a \partial_\mu A_a$$

$$\times \eta^{b\mu} \Rightarrow m \ddot{x}^b - q \dot{x}^a \partial_a A^b = q \dot{x}^a \partial^b A_a$$

$$\therefore m \ddot{x}^b = q (\partial^b A_a - \partial_a A^b) \dot{x}^a$$

swap  $a \leftrightarrow b \Rightarrow m \ddot{x}^a = q (\partial^a A_b - \partial_b A^a) \dot{x}^b$

$$\therefore \ddot{x} = \frac{q}{m} F^a_b \dot{x}^b \quad \text{for } F^a_b = \partial^a A_b - \partial_b A^a$$

Correct!

$$\ddot{x}^a = \frac{q}{m} F^a_b \dot{x}^b, \quad \text{lower } a \text{ gives}$$

$$\ddot{x}_a = \frac{q}{m} F_{ab} \dot{x}^b$$

Contract with  $\dot{x}^a$  gives  $\dot{x}^a \ddot{x}_a = \frac{q}{m} F_{ab} \dot{x}^a \dot{x}^b$

$$F_{ab} \dot{x}^a \dot{x}^b = F_{ba} \dot{x}^b \dot{x}^a = F_{ba} \dot{x}^a \dot{x}^b = -F_{ab} \dot{x}^a \dot{x}^b = 0 =$$

swap a, b

(✓)

F antisymmetric

$$\therefore F_{ab} = \partial_a A_b - \partial_b A_a$$

$$\therefore \dot{x}^a \ddot{x}_a = 0$$

~~$$\therefore \frac{d}{ds} (-\eta_{ab} \dot{x}^a \dot{x}^b)$$~~

$$\therefore \frac{d}{ds} (\dot{x}^a \dot{x}_a) = \dot{x}^a \ddot{x}_a + \ddot{x}^a \dot{x}_a = 2 \underbrace{\dot{x}^a \ddot{x}_a}_{=0} = 0$$

~~$$\therefore \dot{x}^a \dot{x}_a = \text{const}$$~~

$$\therefore \sqrt{-\eta_{ab} \dot{x}^a \dot{x}^b} = \sqrt{-\dot{x}^a \dot{x}_a} = \text{const.}$$

Clear!  
Keep it up.

(7)

(1+)

4-momentum density

directional pressure

~~$J^a = -T^{ab} V_b$~~

$J^a = -T^{ab} V_b$   
(5)

$P_x = \underline{T_{ab} x^a x^b}$  good!

= pressure in direction of  $x^a$

( $x^a$  is such that  $x^a x_a = 1$   
 $U^a x_a = 0$ ).

perfect fluid :

$T^{ab} = (p + \rho) U^a U^b + p \eta^{ab}$

observer also moving with  $U^a$

~~∴ energy density~~

∴ 4 momentum density

$J^a = -T^{ab} U_b = - (p + \rho) \underbrace{U^a U^b U_b}_{(-1)} + p \underbrace{\eta^{ab} U_b}_{U^a}$

=  $+ (p + \rho) U^a - p U^a = \underline{\underline{p U^a}}$

∴  $p = \text{mass density}$  *Great!*

pressure in  $x^a$

~~$P_x = T_{ab} x^a x^b$~~

~~$= (p + \rho) U^a U^b$~~

Good!

$P_x = \underline{T_{ab}} T_{ab} x^a x^b = (p + \rho) \underbrace{U_a U_b x^a x^b}_{=0 \because U_a x^a = U_b x^b = 0} + p \eta_{ab} x^a x^b = p \underbrace{x_a x^a}_{=1} = \underline{\underline{p}}$



normal

$\therefore P = \text{pressure.}$

the tensor  $h^a_b = \delta^a_b + U^a U_b$

$$1. \quad h^a_b U^b = \delta^a_b U^b + U^a \underbrace{U_b U^b}_{-1} \\ = U^a - U^a = 0 \quad \textcircled{v}$$

$$2. \quad h^a_b h^b_c = (\delta^a_b + U^a U_b)(\delta^b_c + U^b U_c) \\ = \delta^a_b \delta^b_c + \delta^a_b U^b U_c + \delta^b_c U^a U_b + U^a \underbrace{U_b U^b U_c}_{-1} \\ = \delta^a_c + U^a U_c + \cancel{U^a U_c} - \cancel{U^a U_c} \\ = \delta^a_c + U^a U_c = h^a_c \quad \textcircled{v}$$

$$3. \quad h^a_a = \underbrace{\delta^a_a}_4 + \underbrace{U^a U_a}_{-1} = 3 \quad \textcircled{v}$$

$h^a_b$  is a ~~proj~~ projector onto hypersurface  $\perp U^a$   
 this is evident  $\neq$   $\because$  we observe that

$$h^a_b U^b = 0 \Rightarrow U^b \text{ projected to surface } \perp U^b \\ \text{is of course } 0$$

$h^a_b h^b_c = h^a_c \Rightarrow$  projecting once and twice  
 $P^2 = P \Rightarrow P$  is projection are essentially the same  
 operation.

$h^a_a = 3 \Rightarrow$  this tensor is correctly normalized  
 to the dimension of hypersurface:  
 e.g., projects onto 3-dim subspace

$$h_{ab} = \eta_{ac} h^c_b = \eta_{ac} (\delta^c_b + U^c U_b)$$

$$= \cancel{\eta_{ab}} \eta_{ab} + U_a U_b$$

Induced metric on orthonormal hypersurface

$$\partial_a T^{ab} = 0 \Rightarrow 0 = \cancel{\partial_a P} (\partial_a P + \partial_a P) U^a U^b + (P+P) U^a \partial_a U^b + (P+P) U^b \partial_a U^a + \eta^{ab} \partial_a P \Rightarrow \textcircled{1}^b$$

Now, project  $\textcircled{1}^b$   $\perp$   $U^b$ :

$$h^c_b \textcircled{1}^b \Rightarrow \cancel{\partial_a P} (\partial_a P + \partial_a P) U^a \underbrace{h^c_b U^b}_0$$

$$+ (P+P) \underbrace{h^c_b U^b}_0 \partial_a U^a$$

$$+ (P+P) h^c_b U^a \partial_a U^b + \eta^{ab} h^c_b \partial_a P = 0$$

$$\Rightarrow (P+P) (\delta^c_b + U^c U_b) (\partial_a U^a) \cancel{h^c_b} \partial_a P = 0$$

$$+ h^{ca} \partial_a P = 0$$

$$\therefore (P+P) \underbrace{U^a \partial_a U^c}_{= \frac{dU^c}{dT}} + (P+P) U^a U^c \underbrace{U_b \partial_a U^b}_{=0}$$

$$+ h^{ca} \partial_a P = 0$$

$$- \frac{dU^c}{dT} = \frac{dx^a}{dT} \frac{\partial U^c}{\partial x^a} = U^a \partial_a U^c \quad (U^a = \frac{dx^a}{dT})$$

$$- 0 = \cancel{\partial_a} \partial_a (U^b U_b) = \underbrace{U^b \partial_a U_b}_{=-1} + U_b \partial_a U^b = 2 U_b \partial_a U^b$$

$$\rightarrow U_b \partial_a U^b = 0$$

$$\therefore (P+P) \frac{\partial U^c}{\partial T} + h^{ca} \partial_a P = 0$$

$$\therefore (P+P) \frac{\partial U^a}{\partial T} + h^{ab} \partial_b P = 0 \quad (2)$$

Project  $(1)^b \parallel U^b$  Fantastic!

$$(1)^b - h^b_a (1)^a :$$

$$0 = \cancel{\partial_a P} (\partial_a P + \partial_a P) U^a U^b + (P+P) \cancel{U^a} \partial_a U^b$$

$$+ \cancel{(P+P) U^a} \partial_b U^a + (P+P) U^b \partial_a U^a + \eta^{ab} \partial_a P$$

$$- \cancel{(P+P) U^b} \partial_b U^a - \cancel{h^{ab}} \partial_b P - (P+P) \cancel{U^a} \partial_a U^b$$

$$- \cancel{(P+P) U^a} \partial_a U^b = \cancel{h^{ab}} \partial_a P - h^{ab} \partial_a P$$

$$= \cancel{h^a_b} (P+P) U^a \partial_c U^b - \cancel{h^{ab}} \partial_a P$$

$$\text{Now } (\eta^{ab} - h^{ab}) \partial_a P = (\cancel{\eta^{ab}} - \cancel{\eta^{ab}} - U^a U^b) \partial_a P$$

$$= -U^a U^b \partial_a P$$

$$\therefore \cancel{\partial_a P} 0 = U^a U^b \partial_a P + \cancel{U^a U^b} \partial_a P + \cancel{(P+P)}$$

$$+ P U^b \partial_a U^a + P U^b \partial_a U^a - \cancel{U^a U^b} \partial_a P$$

$$\Rightarrow 0 = \cancel{U^a U^b} \partial_a P + U^b U^a \partial_a P + U^b P \partial_a U^a$$

$$+ U^b P \partial_a U^a$$

$$= U^b (U^a \partial_a P + P \partial_a U^a + P \partial_a U^a)$$

$$\therefore 0 = U^b (\partial_a (p U^a) + P \partial_a U^a)$$

contract with  $U_b$ , use  $U^b U_b = -1$  gives

$$\partial_a (p U^a) + P \partial_a U^a = 0 \quad (3)$$

Good!

In (2), if we set  $P=0 \Rightarrow \rho \frac{dU^a}{dT} = 0$

$$\Rightarrow \frac{dU^a}{dT} = 0 \Rightarrow \text{following geodesics.}$$

Great!

Non-relativistic approximations:

1.  $U^a = (1, \vec{u})$   $|\vec{u}| \ll 1 \Rightarrow$  speed of fluid flow much less than the speed of light. ( $|\vec{u}| \ll c$ )  
 so  $\gamma \approx 1$   $U^a = (\gamma, \gamma \vec{u}) \approx (1, \vec{u})$  (4)

2.  $P \ll \rho \Rightarrow$  kinetic energy much less than rest mass energy ( $P \ll \rho c^2$ )  $\frac{P}{c^2} \ll \rho$  (5)

3.  $|\vec{u}| \partial_t P \ll |\vec{\nabla} P|$  ( $\frac{|\vec{u}|}{c^2} \partial_t P \ll |\vec{\nabla} P|$ )

two parts:  $\frac{|\vec{u}|}{c} \ll 1$  (obvious)

And  $\frac{1}{c} \frac{\partial}{\partial t} P \ll |\vec{\nabla} P| = \left| \frac{\partial P}{\partial \vec{x}} \right|$  this is

because fluid non-relativistic  $\therefore c dt \gg |d\vec{x}|$

$\Rightarrow \partial_t \ll |\vec{\nabla}|$   
 (consistent)

Good!

Scalar equation :

$$\partial_a (\rho U^a) + P \partial_a U^a = 0$$

$$\therefore \partial_t (\rho \cdot 1) + \vec{\nabla} \cdot (\rho \vec{u}) = 0$$

$$+ P (\cancel{\partial_t 1} + \vec{\nabla} \cdot \vec{u}) = 0$$

$$\therefore \partial_t \rho + \vec{\nabla} \cdot (\rho \vec{u}) + P (\vec{\nabla} \cdot \vec{u}) = 0$$

$$\because P \ll \rho \quad \therefore |P (\vec{\nabla} \cdot \vec{u})| \ll |\vec{\nabla} \cdot (\rho \vec{u})|$$

$$\therefore \underline{\underline{\partial_t \rho + \vec{\nabla} \cdot (\rho \vec{u}) = 0}} \quad \text{Good!}$$

~~Vector equation~~

(also compare  $|\partial_t \rho|$  and  $|\vec{\nabla} \cdot (\rho \vec{u})|$ )

lets see that

$$\partial_t \ll \vec{\nabla}$$

$$P \ll \rho$$

$$|\vec{u}| \ll 1$$

$$|P (\vec{\nabla} \cdot \vec{u})|$$

and  $\partial_t \ll |\vec{\nabla}|$  by the same order as  $|\vec{u}| \ll 1$

$\therefore$  since  $P \ll \rho$

$$\therefore |\partial_t \rho| \gg |P (\vec{\nabla} \cdot \vec{u})|$$

$\downarrow$  they both represent non-relativistic speed of fluid

Vector equation :

$$(\rho + P) \frac{dU^a}{dt} + h^{ab} \partial_b P = 0$$

$$h^{ab} = \eta^{ab} + U^a U^b$$

$$\therefore (\rho + P) U^b \partial_b U^a + \eta^{ab} \partial_b P + U^a U^b \partial_b P = 0$$

$$\because P \gg \rho \quad \therefore \rho + P \approx P \quad \text{Good!}$$

$$\therefore P U^b \partial_b U^a + \partial^a P + U^a U^b \partial_b P = 0$$

$$\cancel{U^b \partial_b = \partial_t + \vec{u} \cdot \vec{\nabla}} \quad U^b \partial_b = (\partial_t + \vec{u} \cdot \vec{\nabla})$$

$$\cancel{U^b \partial_b U^a = \dots}$$

- consider  $a=0$  :

$$\therefore U^0 = 1$$

$$\therefore U^b \partial_b U^0 = 0$$

$$\partial^0 P + (1) U^b \partial_b P = 0$$

$$\therefore -\partial_t P + \cancel{(\partial_t + \vec{u} \cdot \vec{\nabla})} P = 0 \Rightarrow \vec{u} \cdot \vec{\nabla} P = 0$$

not true, this degree of approximation doesn't work for this one.

- consider  $a=i$  &  $i \in \{1, 2, 3\}$

$$P U^b \partial_b U^i + \partial^i P + U^i U^b \partial_b P = 0$$

$$\therefore \cancel{P(\partial_t + \vec{u} \cdot \vec{\nabla})} P(\partial_t + \vec{u} \cdot \vec{\nabla}) \vec{u} + \vec{\nabla} P + \cancel{\vec{u}(\vec{u} \cdot \vec{\nabla}) P} = 0$$

①
②
③

$$\cancel{|\vec{u} \cdot \vec{\nabla} P| \ll |\vec{\nabla} P|} \quad \because |\vec{u}| \ll 1 \quad \therefore \textcircled{3} \ll \textcircled{2}$$

$$\cancel{|P \partial_t \vec{u}|}$$

$$\therefore |\vec{u} \partial_t P| \ll |\vec{\nabla} P|, \quad \vec{u}(\vec{u} \cdot \vec{\nabla} P) \ll |\vec{u}|$$

$$\therefore |\vec{u}| \ll 1$$

$$\therefore \textcircled{3} \ll \textcircled{2}$$

$$|P \partial_t \vec{u}| \gg |\vec{u} \partial_t P| \quad \because \rho \gg P \quad \therefore \textcircled{1} \gg \textcircled{3}$$

$\therefore \textcircled{3}$  neglected

good!

$$\therefore P(\partial_t + \vec{u} \cdot \vec{\nabla}) \vec{u} = -\vec{\nabla} P$$